

Monotone Submodular Multiple Knapsack

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Set function properties

▶ Let N be a universe of elements and $f: 2^N \rightarrow \mathbb{R}_{\geq 0}$ be a set function

▶ Monotone - if $\forall A \subseteq B$ then $f(A) \leq f(B)$

▶ Marginal value - for every $A, B \subseteq N$ we define as

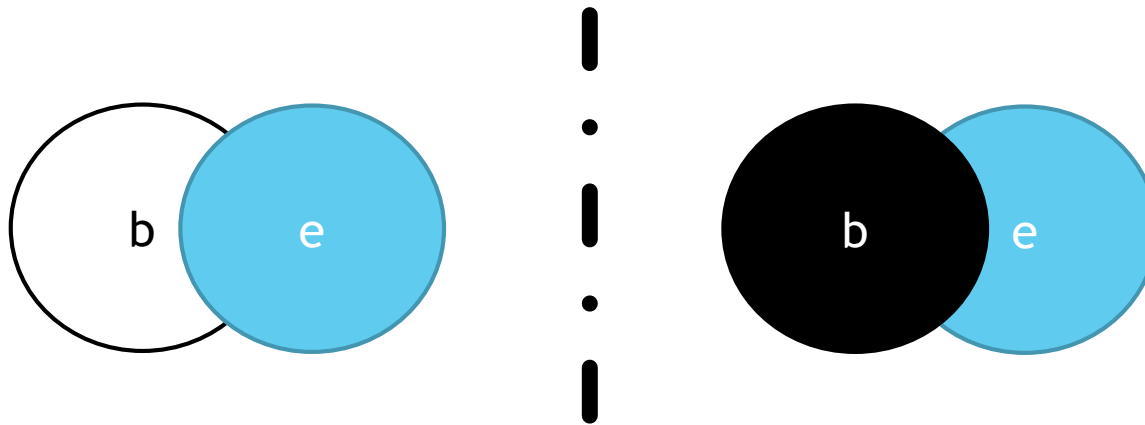
$$f_A(B) = f(A \cup B) - f(A)$$

▶ Submodular - if for any $A \subseteq B \subseteq N, e \in N \setminus B$

$$f_A(\{e\}) \geq f_B(\{e\})$$

Submodular function examples

- ▶ Coverage function (also monotone)
- ▶ $A = \emptyset, B = \{b\}$



- ▶ Other examples: cut (non monotone), rank (monotone)

Multilinear extension

- ▶ The multilinear extension $F: [0,1]^N \rightarrow \mathbb{R}_{\geq 0}$ of a f :
 - ▶ $F(\vec{x}) = E[f(T)]$, where $T \sim \vec{x}$ ($i \in T$ w.p. x_i)
 - ▶ $F(\mathbf{1}_T) = f(T)$
 - ▶ Extends to continuous domain
- ▶ Continuous greedy can find $\vec{x} \in P$ such that $F(\vec{x}) \geq \left(1 - \frac{1}{e} - \epsilon\right) \cdot OPT$
 - ▶ P is the relaxed polytope (describing the constraints)

Multiple Knapsack problem (MKP)

- ▶ Input:

- ▶ A set of items I with

- ▶ weight w_i

- ▶ profit p_i for each $i \in I$

- ▶ $|I| = n$

- ▶ A set of bins B with

- ▶ capacity W_b for each $b \in B$

- ▶ $|B| = m$

Multiple Knapsack problem (MKP)

- ▶ Output:

- ▶ Feasible set $T \subseteq I$ for which there exists an assignment $A = (A_1, \dots, A_m)$

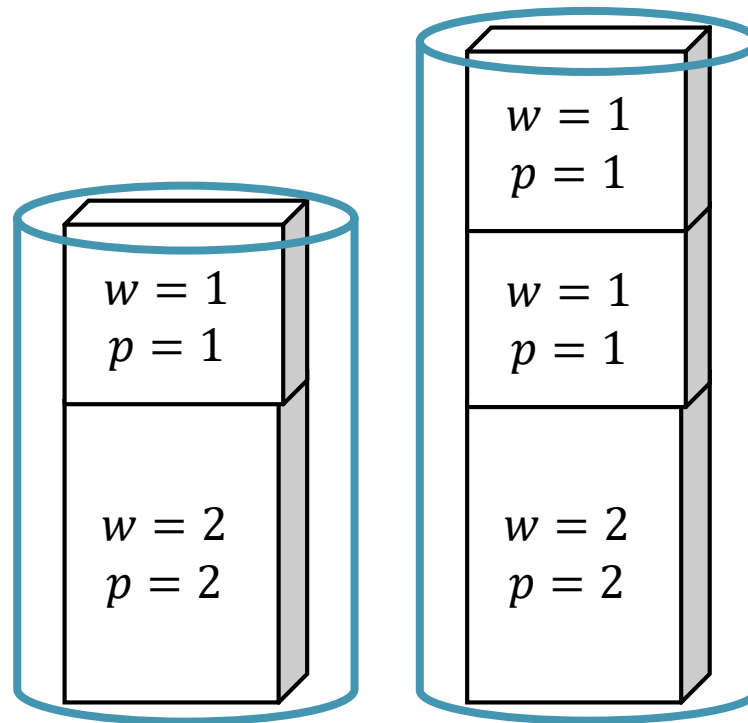
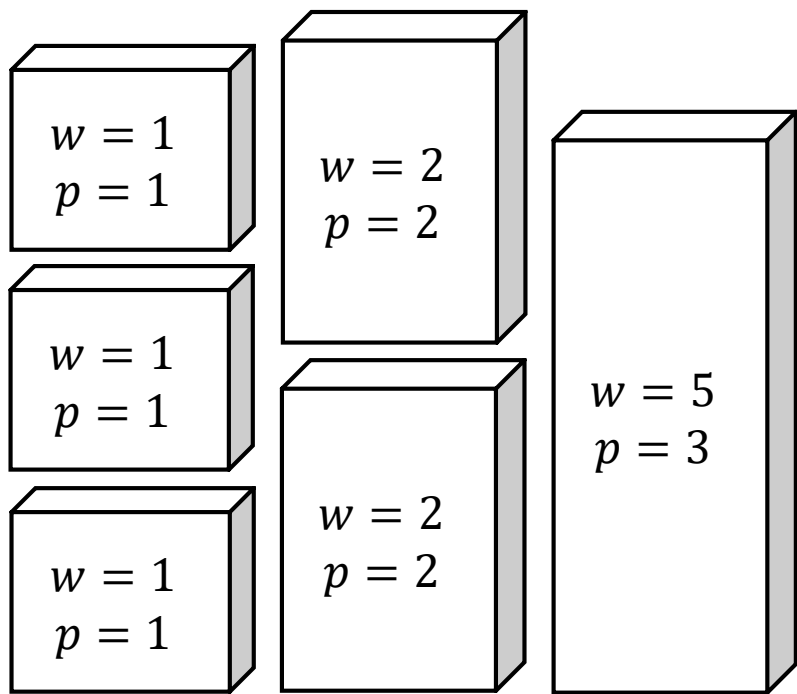
- ▶ $\sum_{i \in A_b} w_i \leq W_b$ for all $b \in B$

- ▶ $\bigcup_{b \in B} A_b = T$

- ▶ Goal:

- ▶ Find feasible T which maximizes $\sum_{i \in T} p_i$

Example



$$W_1 = 3$$

$$W_2 = 5$$

Monotone Submodular MKP (SMKP)

▶ Input:

▶ MKP constraint:

▶ Set of items I with weights w_i

▶ Set of bins B with capacities W_b

▶ Monotone submodular objective function $f: 2^I \rightarrow \mathbb{R}_{\geq 0}$

▶ Output:

▶ Feasible set $T \subseteq I$ with assignment A

▶ Goal:

▶ Find feasible set T which maximizes $f(T)$

Our Results

- ▶ A random polynomial time $(1 - \frac{1}{e} - \epsilon)$ -approximation algorithm for Monotone SMKP for any $\epsilon > 0$.
- ▶ Known hardness - cannot be approximated within $(1 - \frac{1}{e} + \epsilon)$
 - ▶ follows hardness subject to cardinality constraint
 - ▶ in the oracle model - [Nemhauser, Wolsey. 1978]
 - ▶ unless $P \neq NP$ for coverage functions - [Feige. 1998]

Related work

- ▶ $(1 - \frac{1}{e})$ -approximation for **constant** number of bins - [Sviridenko. 2003]
- ▶ $(1 - \frac{1}{e} - \epsilon)$ -approximation for multidimensional knapsack (for constant dimension) - [Kulik, Shachnai, Tamir. 2009]
- ▶ Deterministic $(1 - \frac{1}{e} - \epsilon)$ -approximation for Monotone SMKP for **uniform bin capacity** - [Sun, Zhang, Zhang. 2020]
 - ▶ Randomized $(1 - \frac{1}{e} - \epsilon)$ -approximation for **restricted instances** of Monotone SMKP (improved later for general instances)
 - ▶ **Parallel work to ours**

Uniform SMKP

- ▶ A special case of SMKP: the Uniform SMKP
 - ▶ for each pair of bins b_1, b_2 it holds that $W_{b_1} = W_{b_2}$
 - ▶ for simplicity assume $W_b = 1$ for all $b \in B$
- ▶ For constant $\mu > 0$, split I to sets L, S of large and small items
 - ▶ if $w_i \geq \mu$, item i is said to be large
 - ▶ else, i is said to be small
- ▶ Configuration $c \subseteq L$ is a set of large items s.t. $\sum_{i \in c} w_i \leq 1$
 - ▶ $|c| \leq \mu^{-1}$
 - ▶ Let C be the set of configurations, then $|C| \leq n^{\mu^{-1}}$

Relaxation

- ▶ New set of items $E = \{e \subseteq I \mid e \in C \text{ or } e = \{i\} \subseteq S\}$
- ▶ At most one “maximal” configuration is assigned to each bin
- ▶ Swap all bin constraints by a two dimensional “bin”:
 - ▶ The bin (solution) contains at most m configurations
 - ▶ The total weight of items and configurations is m
- ▶ New objective function $g: 2^E \rightarrow \mathbb{R}_{\geq 0}$ defined as $g(T) = f(\cup_{e \in T} e)$
 - ▶ maintains monotonicity and submodularity

Algorithm

▶ Phase 1

- ▶ Solve using continuous greedy (w.r.t. multilinear extension), get solution \vec{x}
- ▶ Select random set $T \sim \vec{x}$
- ▶ If T violates one of the two constraints, return an empty solution

▶ Phase 2

- ▶ Assign each configuration $c \in T$ to a different bin
- ▶ Assign small items in T using First-Fit (add bins as necessary)
- ▶ Discard worst bins

Analysis - Phase 1

- ▶ Due to guarantees of the continuous greedy and the multilinear extension

$$\mathbb{E}[f(T)] \geq \left(1 - \frac{1}{e} - \epsilon\right) \cdot OPT$$

- ▶ What is the probability that T violates a constraint?
- ▶ Chernoff bounds yields $\Pr[T \text{ violates a constraint}] \leq e^{O(-\mu^2 m)}$
 - ▶ We lose a factor of $1 - e^{O(-\mu^2 m)}$

Analysis - Phase 2

- ▶ What is the loss due to discarded bins/items?
- ▶ Once First-Fit finishes bins are almost full
 - ▶ the size of items is at most μ
 - ▶ free capacity in all but one bin is at most μ
 - ▶ assigned weight to added bins is at most $\mu \cdot m$
 - ▶ at most $O(\mu^2 \cdot m)$ bins were added
 - ▶ $\frac{O(\mu^2 \cdot m)}{1+O(\mu^2 \cdot m)}$ of the bins are discarded
- ▶ Final approximation - $\left(1 - \frac{1}{e} - \epsilon - e^{O(-\mu^2 m)} - O(\mu)\right) \cdot OPT$

Observations

- ▶ For some $\epsilon' = \epsilon + e^{O(-\mu^2 m)} + O(\mu)$ we get the desired ratio
- ▶ Larger values of m lead to better approximation
 - ▶ Small bid assumption
- ▶ How well does the algorithm perform on general bin capacities?

SMKP

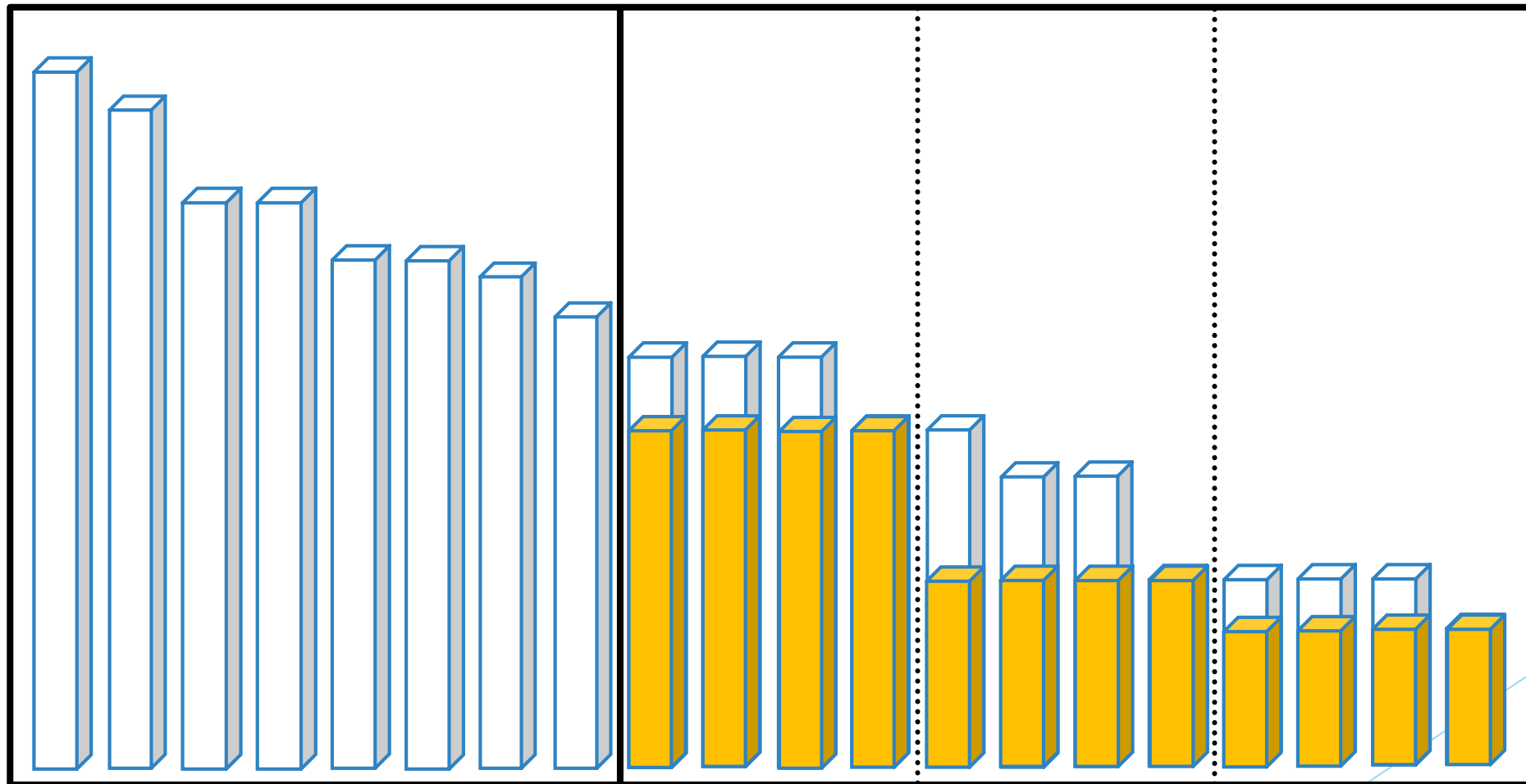
- ▶ Block: a set of bins K is called a block if $\forall b_1, b_2 \in K, W_{b_1} = W_{b_2}$
- ▶ Let $B = K_1 \cup \dots \cup K_t$ then the previous algorithm guarantees

$$\left(1 - \frac{1}{e} - \epsilon - \sum_{j=1}^t e^{O(-\mu^2 |K_j|)} - O(\mu) \right) \cdot OPT$$

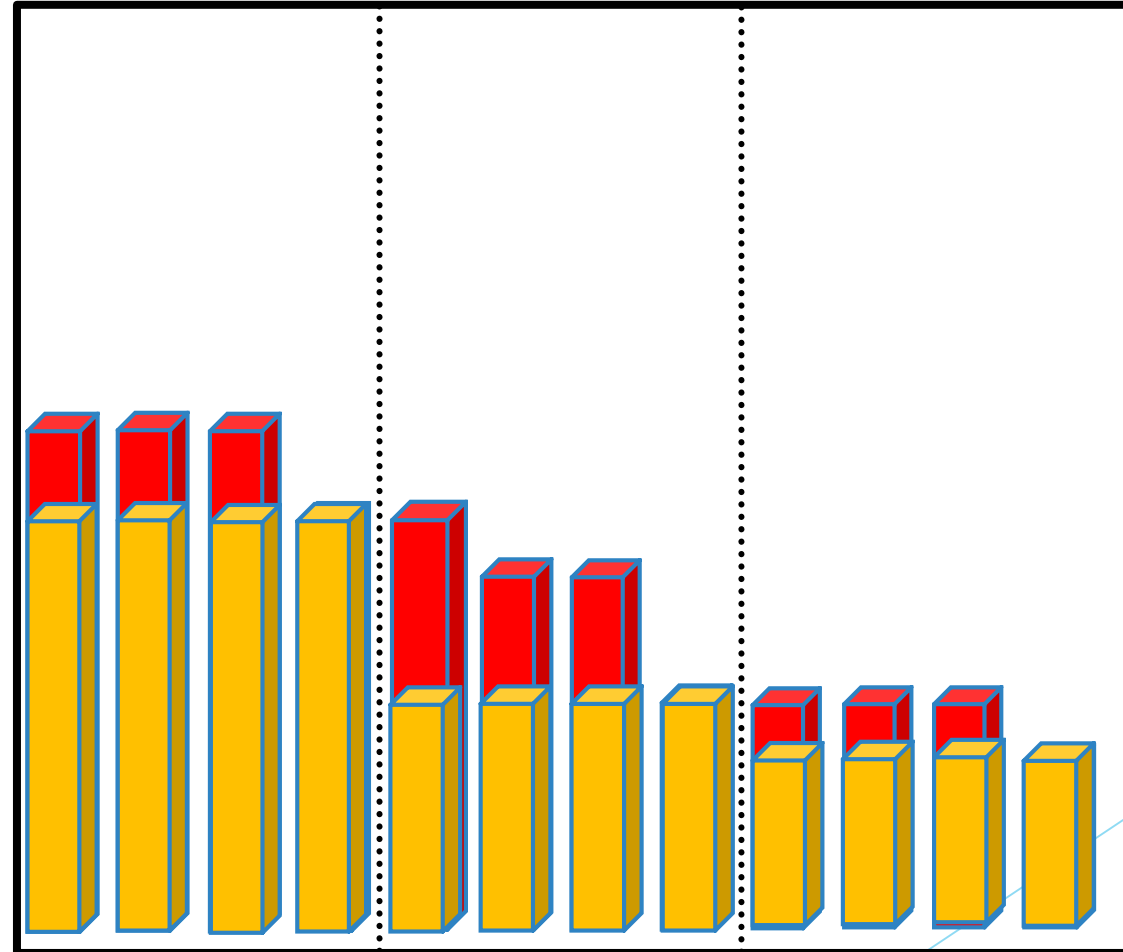
- ▶ We might have many small blocks...
 - ▶ Note - we can handle few small blocks (enumeration)
- ▶ Can we decrease the number of small blocks?

Structuring (by grouping)

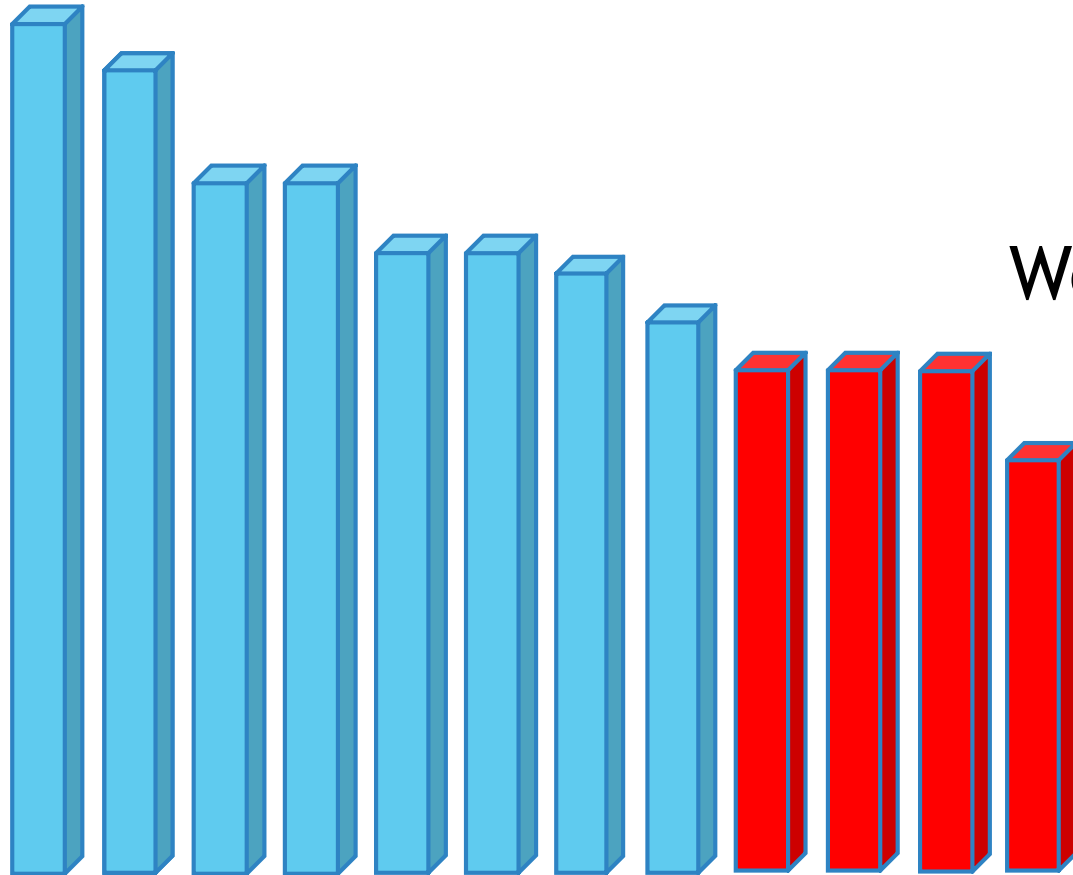
What is the loss?



Structuring loss

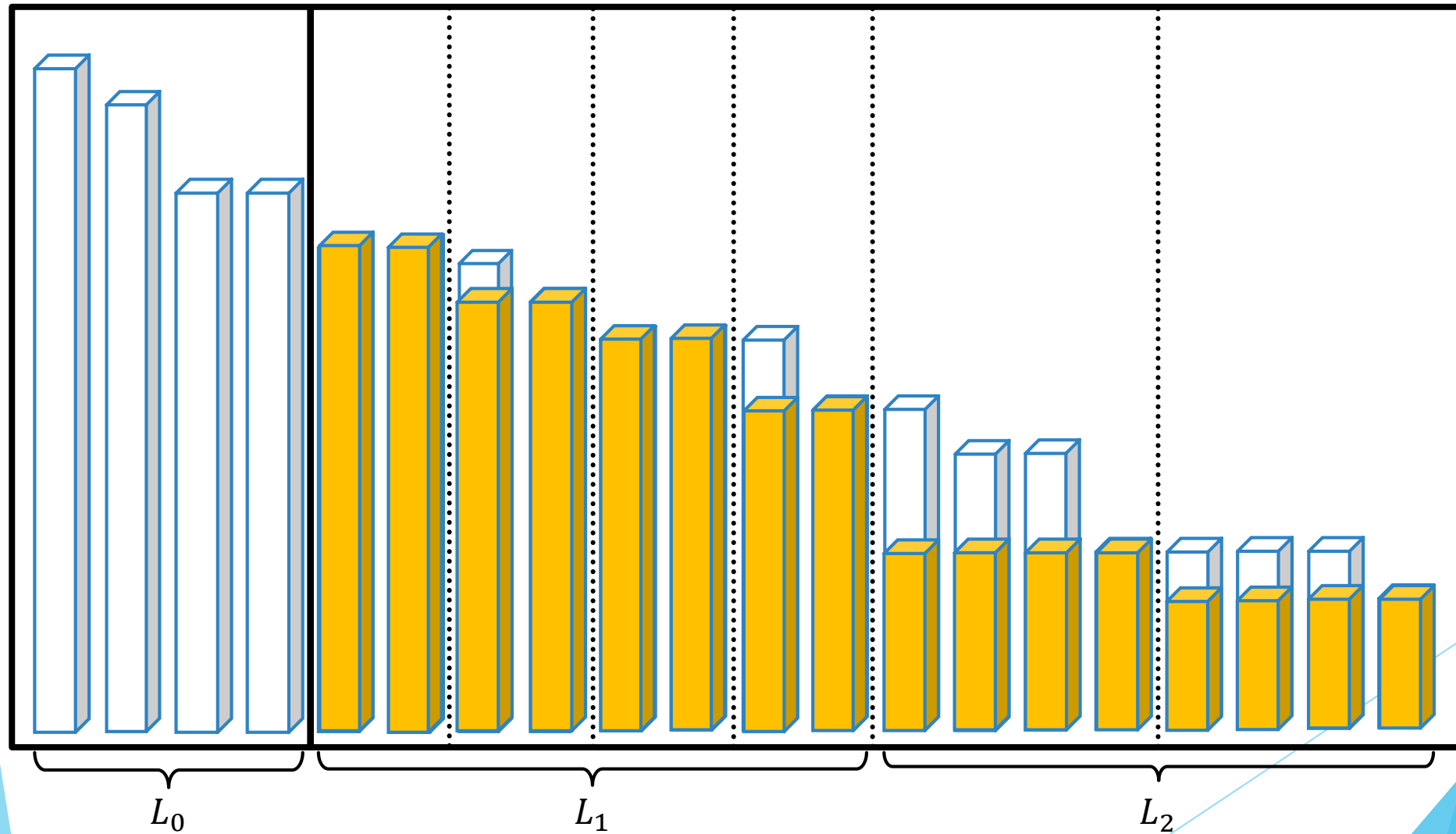


Structuring loss



We lose - $\frac{\textit{block size}}{\textit{\#singletons}}$

Structuring



N-leveled instances

Level	#Blocks	Block size	#Bins
0	N^2	1	N^2
1	N^2	N	N^3
2	N^2	N^2	N^4
3	N^2	N^3	N^5

- ▶ Structuring loss on every level: $1 - \frac{1}{N}$
- ▶ Level size grows exponentially
- ▶ Small number of small blocks
- ▶ Rounding loss converges

Algorithm

- ▶ Enumerate - guess the assignment of a constant number of items
- ▶ Structure - adjust capacities to get an N -leveled instance
- ▶ Solve - using the continuous greedy algorithm (w.r.t. multilinear extension)
- ▶ Round - randomly according to the fractional solution
- ▶ Assign - to each block using First-Fit

Discussion

- ▶ Does the algorithm generalize to natural extensions?
 - ▶ Multiple - multiple knapsacks
 - ▶ Intersecting matroid constraints
 - ▶ Non-monotone objective function
 - ▶ Curvature (maximum decrease in marginal value)
- ▶ No! because we changed the objective function

Discussion

- ▶ $O(1)$ multiple knapsacks constraints
 - ▶ Different configurations in different set of knapsacks
- ▶ Matroid constraints
 - ▶ Matroid properties are lost due to configurations
 - ▶ Cardinality constraint - non-uniform “size” for each element
- ▶ Non-monotone objective function
 - ▶ If not monotone, submodularity isn't maintained
- ▶ Curvature (maximum decrease in marginal value)
 - ▶ Curvature of new objective function is always one

Extensions

- ▶ F, Kulik, Shachnai. "Tight Approximations for Modular and Submodular Optimization with d-Resource Multiple Knapsack Constraints." arXiv.
 - ▶ "Insert" the configurations into the constraints
 - ▶ Extends to:
 - ▶ Multiple - multiple knapsacks constraints
 - ▶ Matroid constraints
 - ▶ Non-monotone (same approximation as single knapsack constraint)
- ▶ A $\left(1 - \frac{1}{e} - o(1)\right)$ -approximation for Uniform SMKRP

Thank you!

The background features abstract, overlapping geometric shapes in various shades of blue, ranging from light sky blue to deep navy blue. These shapes are primarily located on the right side of the frame, creating a modern, layered effect against the white background.